



CISSOID
POWER SEMICONDUCTORS

SIC INVERTER PLATFORM WEBINAR

27 February 2025

INTRODUCTION

Agenda

- SiC Intelligent Power Modules & Inverter Control Modules
- Modular SiC Inverter Platform (+ Software)
- SiC Inverter Reference Designs

- Case studies:
 - Dead Time Compensation & Optimized Pulse Patterns
 - Reduction of noise & vibration results
 - Efficiencies achieved

- Q&A

Presenters



Pierre Delatte
Chief Technology Officer

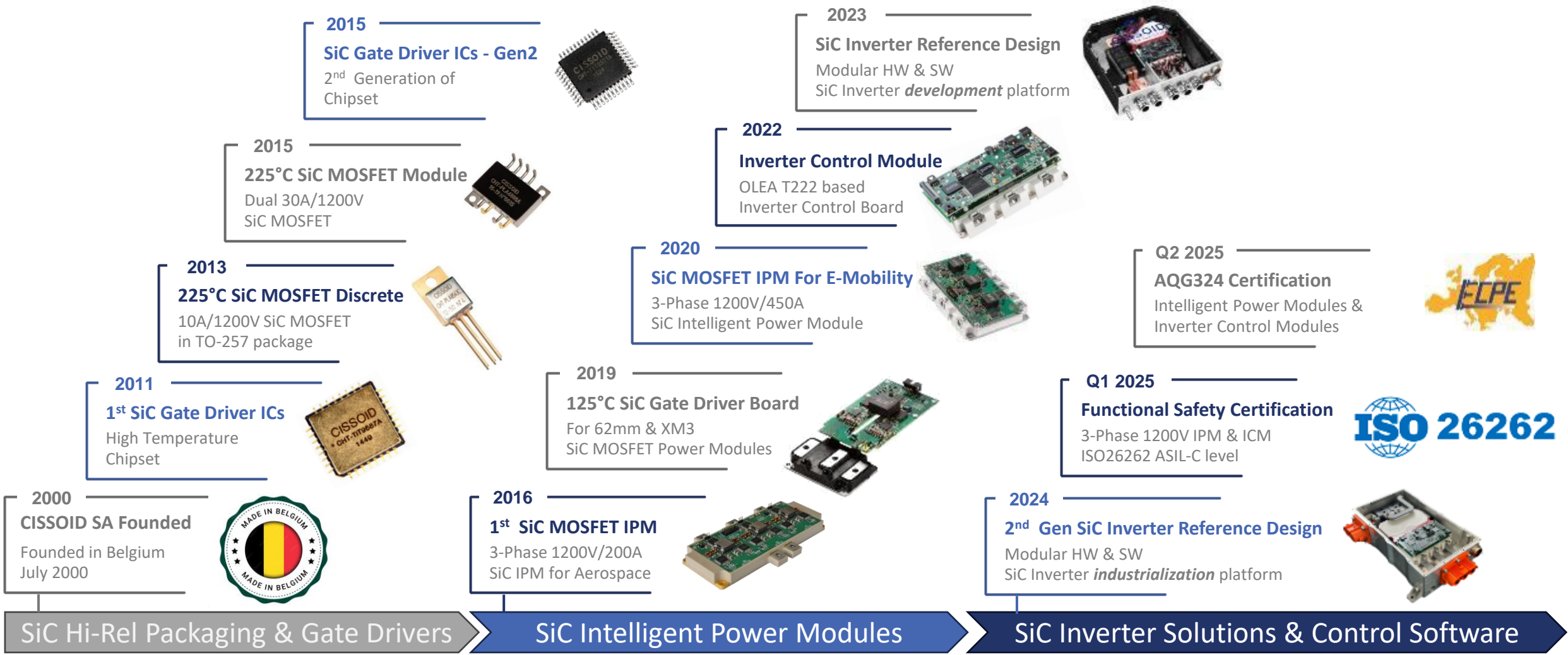


Mike Sandyck
Marketing Director



CISSOID AT A GLANCE

SILICON CARBIDE INNOVATION SINCE 2011



GLOBAL ELECTRIFICATION IS CREATING MULTIPLE OPPORTUNITIES FOR SiC BESIDES MAINSTREAM EVs



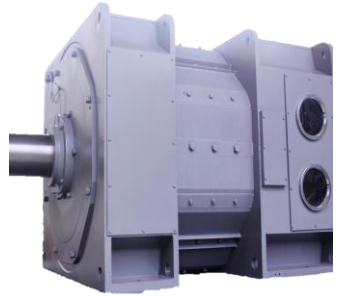
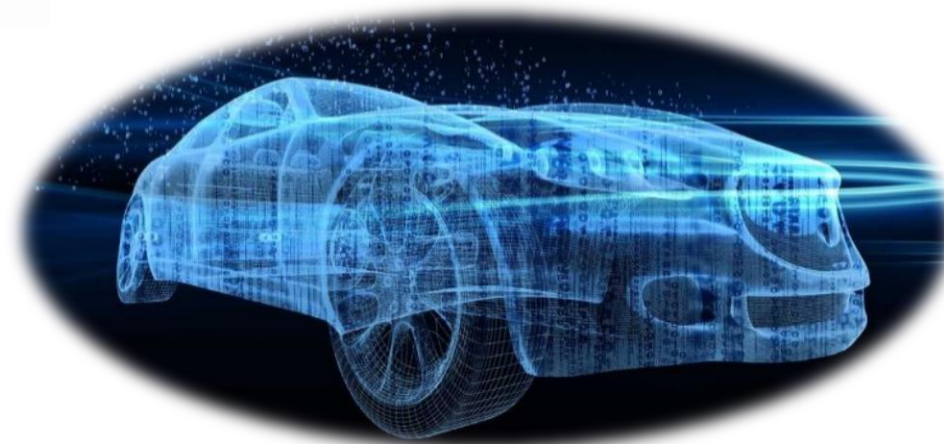
Heavy duty vehicles



E-Boats



E-Aviation



Industrial motor control



E-Busses



Autonomous vehicles



EV Supercars

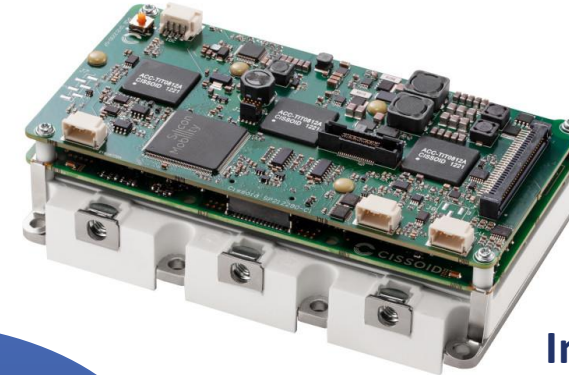
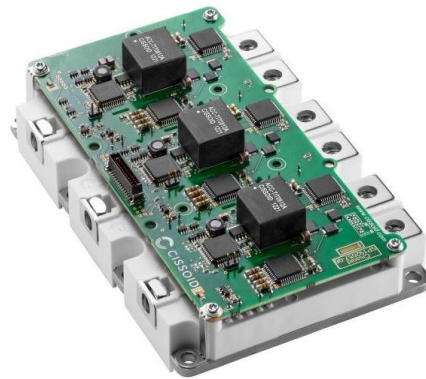


E-Trucks

A UNIQUE MODULAR SiC INVERTER PLATFORM

BASED ON A SUITE OF HARDWARE & SOFTWARE PRODUCTS

3-Phase 1200V/340A-550A
SiC Intelligent Power Module
(IPM)



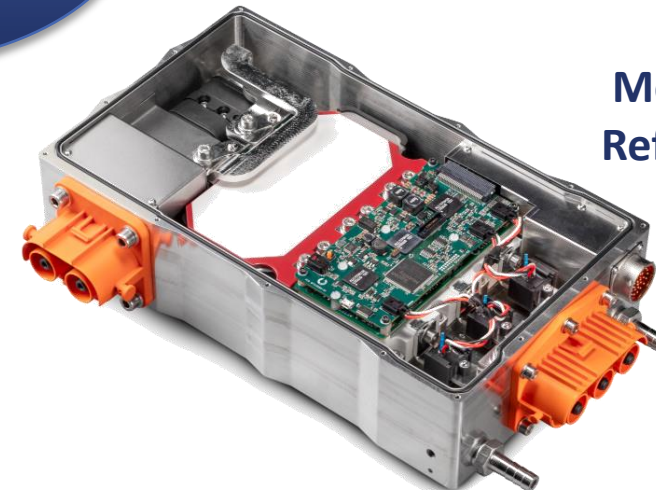
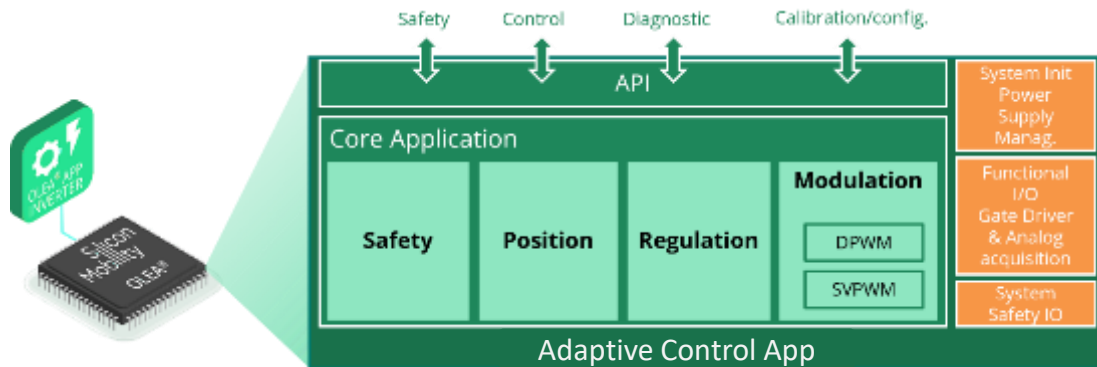
3-Phase 1200V SiC
Inverter Control Module
(ICM)



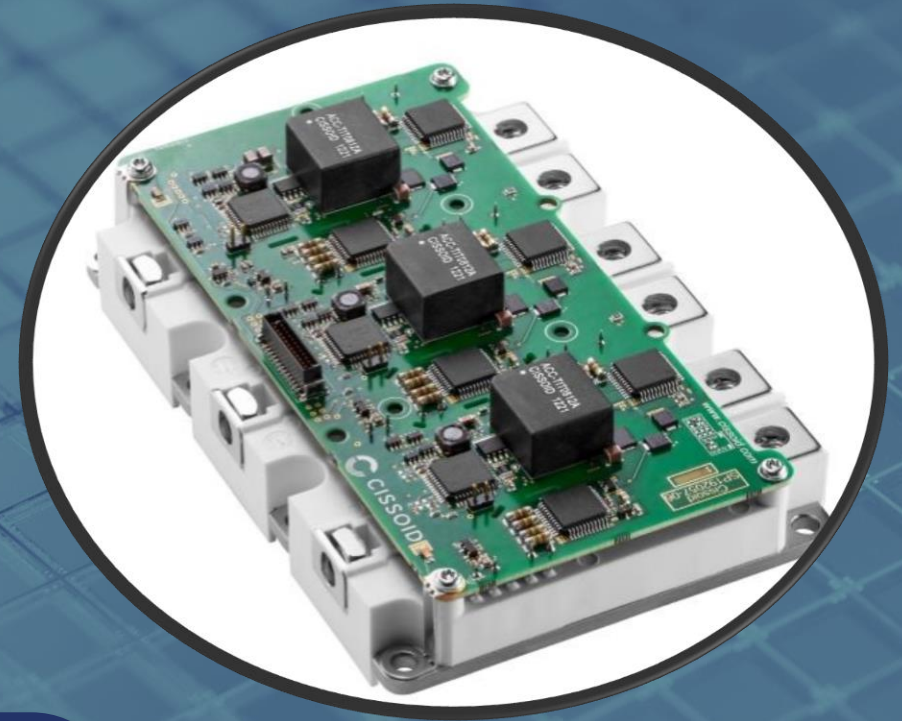
Functionally Safe
E-Motor Control
Hardware & Software
from Intel Automotive



Accelerate your
Time-to-market



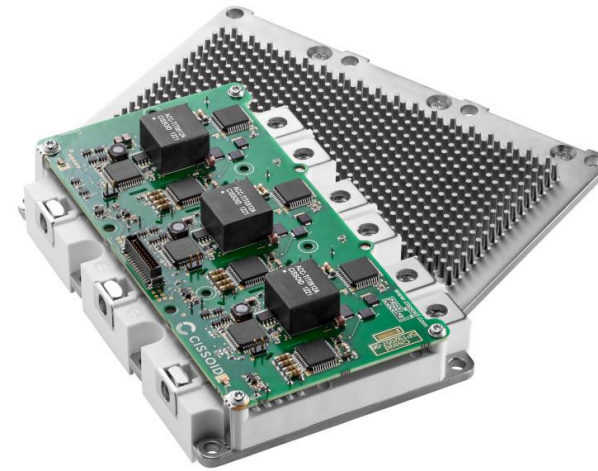
Modular Inverter
Reference Designs



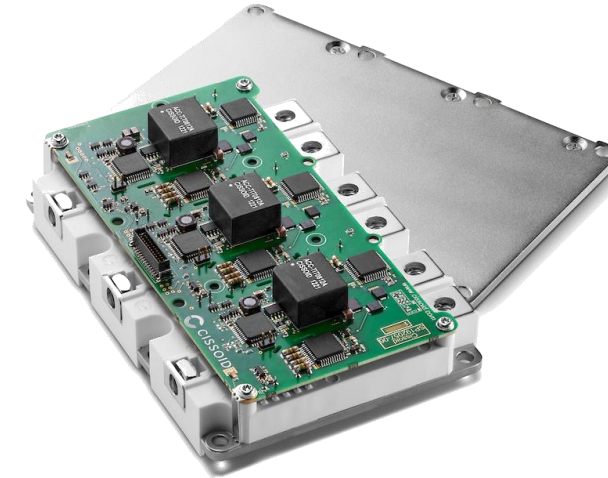
SIC INTELLIGENT POWER MODULE

3-PHASE 1200V SiC MOSFET INTELLIGENT POWER MODULES (IPM)

- Drain-Source breakdown voltage: **1200V**
- Low On-Resistance: **2.53mΩ** to **4.2mΩ**
- Max Continuous Current: **340A_{RMS}** to **550A_{RMS}**
- Max Switching Frequency: **50kHz**
- High Isolation Grade: **>3.6KVrms**
- Low Switching Energies
- Extended Operating Temperature
- Lightweight AlSiC baseplate: **550 - 590g**



Pin Fin (liquid cooling)

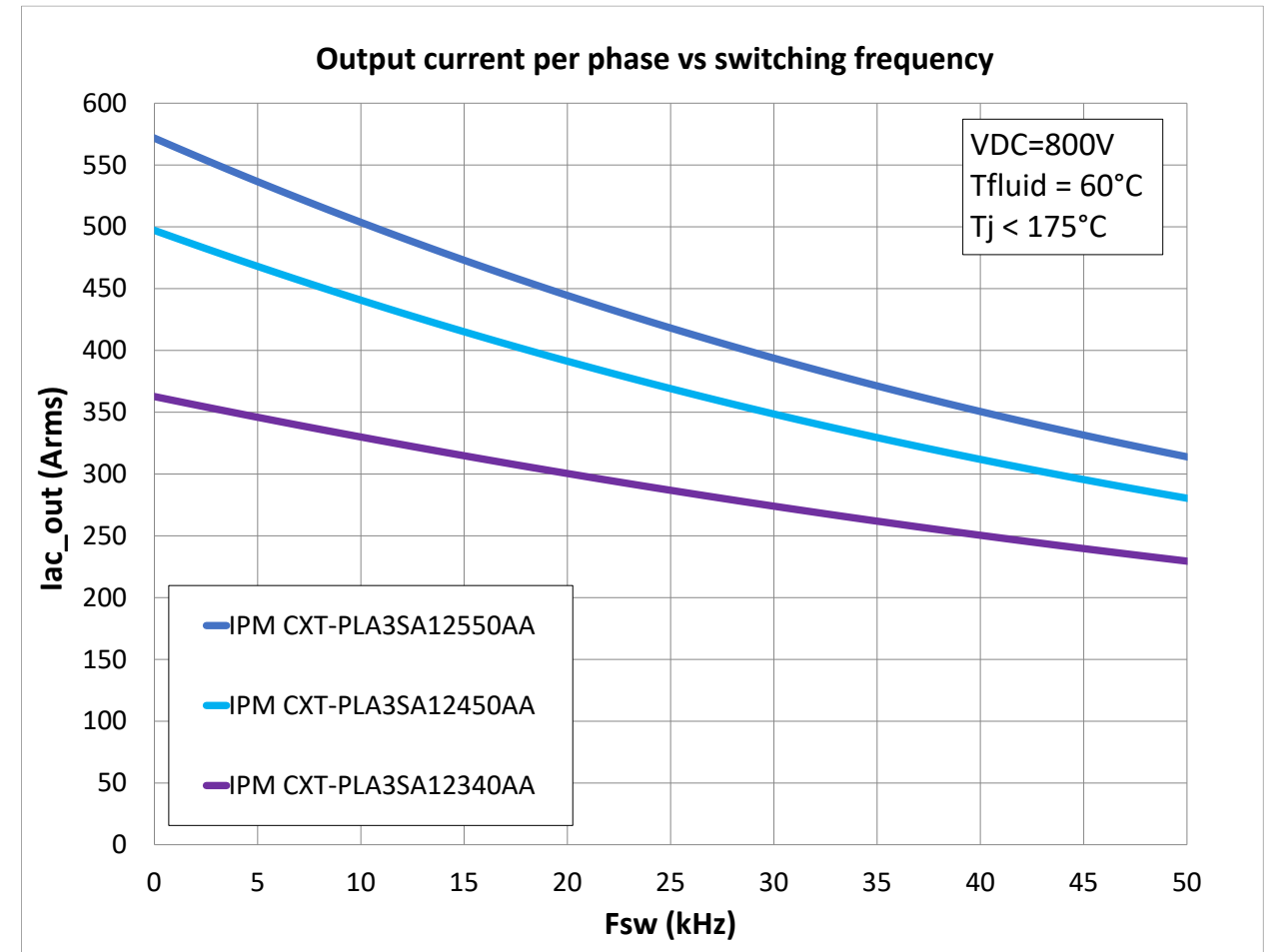


Flat baseplate

Part Number	Max V _{DS}	Max I _{DC} @ 25°C/90°C	Typ. Ron @25°C/175°C	Eon @300A/600V	Eoff @300A/600V	Baseplate	Rthjc
CXT-PLA3SA12340AA	1200V	340A/260A	4.2mΩ/7.64mΩ	7.48mJ	7.39mJ	Pin fin	0.167°C/W
CXT-PLA3SA12450AA	1200V	450A/350A	3.25mΩ/5.15mΩ	8.42mJ	7.05mJ	Pin fin	0.130°C/W
CXT-PLA3SA12550AA	1200V	550A/400A	2.53mΩ/4.4mΩ	9mJ	7mJ	Pin fin	0.119°C/W
CMT-PLA3SB12340AA	1200V	340A/255A	3.25mΩ/5.15mΩ	8.42mJ	7.05mJ	Flat	0.183°C/W

THERMALLY ROBUST IPMs

- **Max junction temperature of power transistors: 175°C**
- **Junction-to-Fluid thermal resistance¹: 0.16°C/W at 10l/min flow rate**
(50% ethylene glycol, 50% water, 75°C inflow temperature)
- **Junction-to-case thermal resistance¹: 0.119°C/W**
- **Temperature robust gate driver board with Max Ambient Temperature up to 125°C**



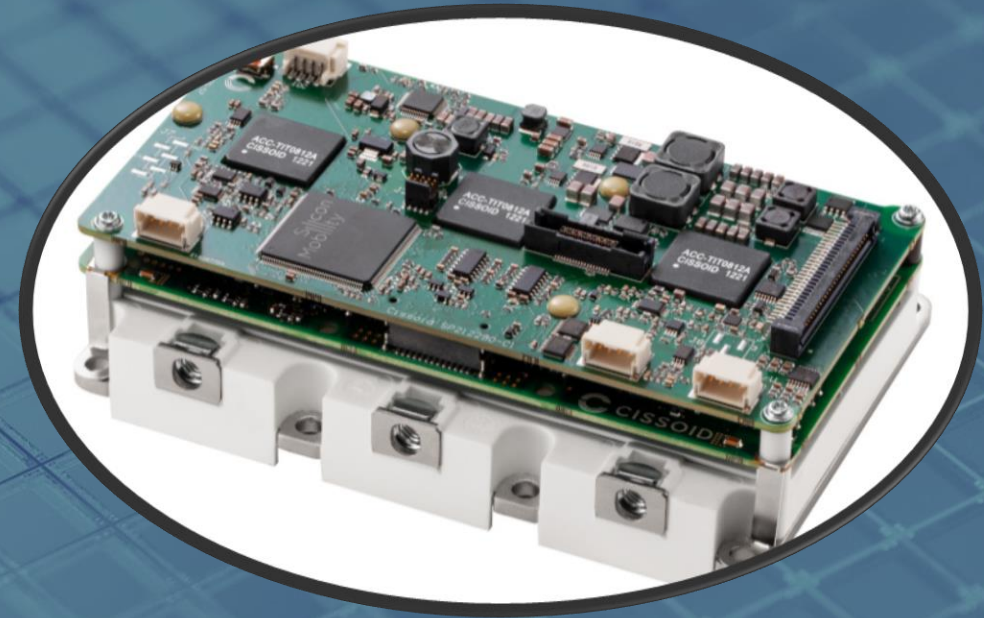
Note 1 : for CXT-PLA3SA12550AA

SiC GATE DRIVERS – GEN2

Optimized to drive SiC MOSFETs

- High peak current for fast switching: **> 10A**
- Robust against high dV/dt: **> 50kV/μs**
- High temperature for high power density: **T_{amb} > 125°C**
- Accurate gate driver voltages: **< +/-5%**
- Protection functions
 - UVLO (primary and secondary sides)
 - Desaturation Detection & Soft Shutdown
 - Negative drive & Active Miller Clamp (AMC) for robustness against parasitic turn-On
 - PWM glitch filter
 - PWM anti-overlap protection

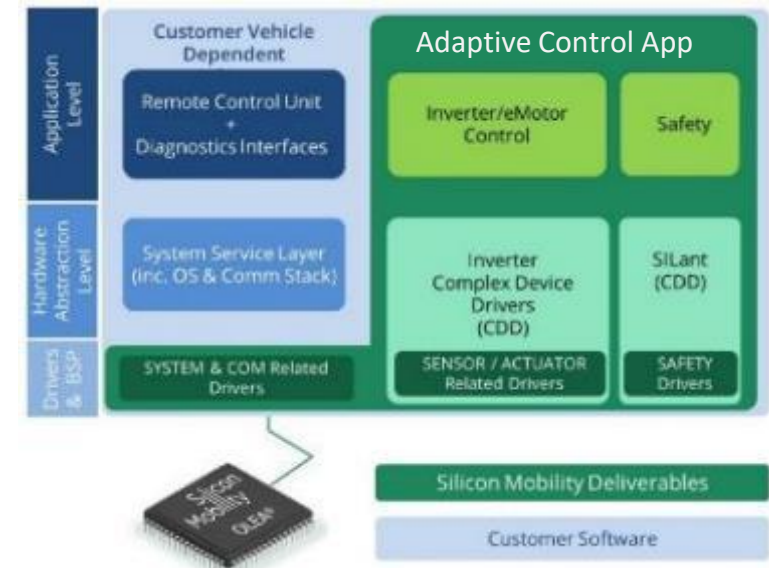
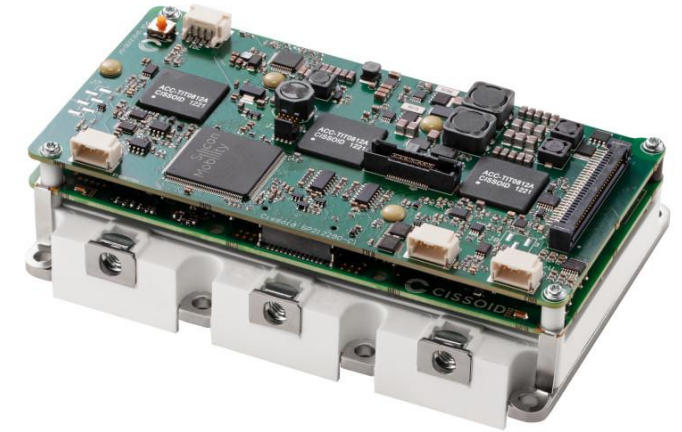




SiC INVERTER CONTROL MODULE

SiC INVERTER CONTROL MODULE (ICM)

- **Control Board** mechanically & electrically integrated with the SiC IPM based on **Adaptive Control Unit (ACU) T222** by **Intel Automotive**
- **ICM Interfaces**
 - Power module: 3-Phase outputs & 3x2 Power Supply Pins
 - Motor: Position Sensor (Resolver, Sin/Cos), current/temperature sensors
 - Vehicle: CAN & Battery supply
 - Developer: SWD (debug) & Trace Port Unit (real-time debug & calibration)
- **Adaptive Control App (ACA)** by **Intel Automotive**
 - Highly configurable inverter & motor control software
 - Advanced control algorithms for highly energy-efficient systems
 - Closed-loop current control based on Field Oriented Control regulation
 - SVPWM and DPWM modulation up to 50 kHz or Optimized Pulse Patterns



ADAPTIVE CONTROL UNIT (ACU) T222

- **Ultra-fast real-time processor by Intel Automotive**
System-level fault detection, correction and containment in tens of nanoseconds

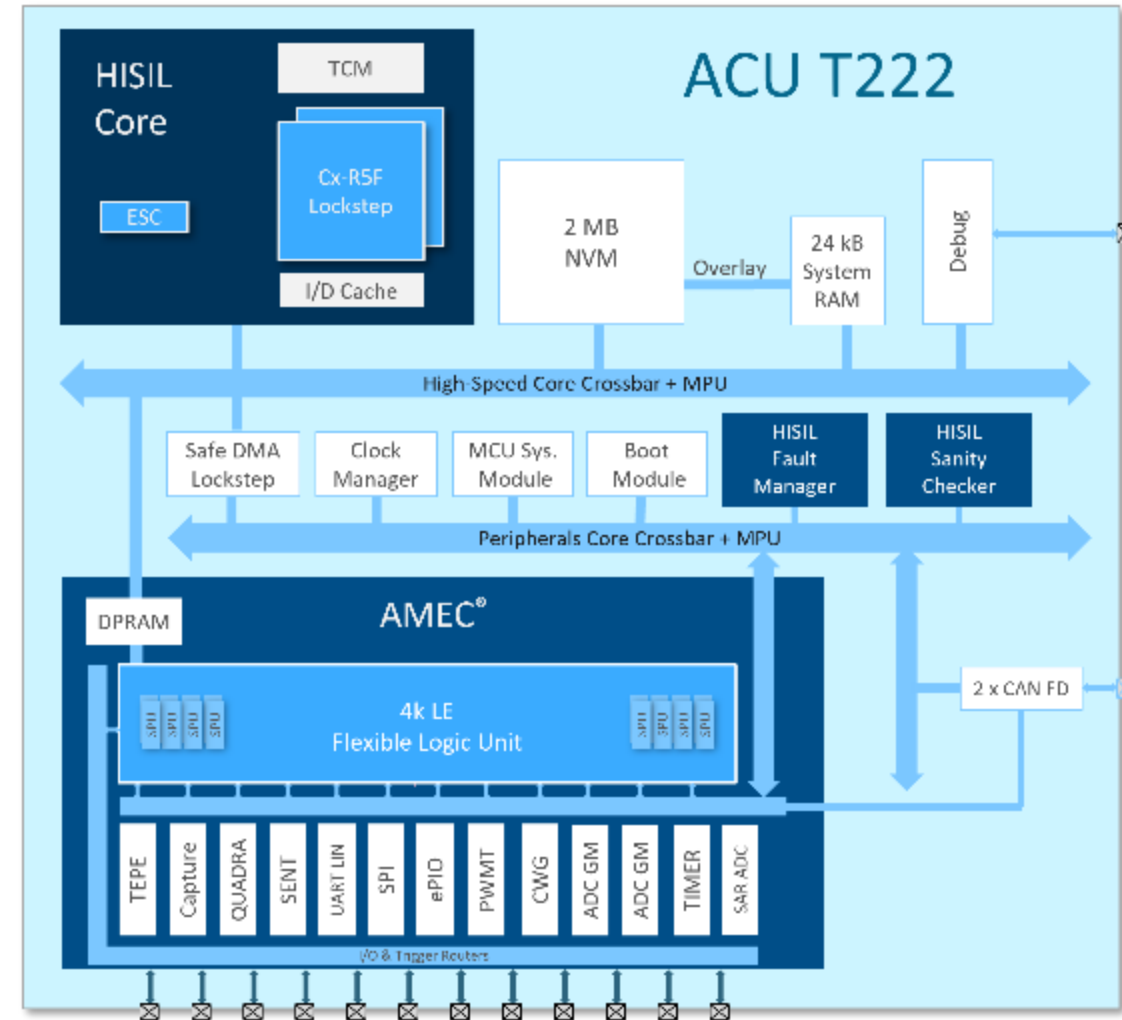
- 40x faster processing compared to standard MCUs
- 1000x faster fault detection compared to standard solutions
- Real-time - 100% timing predictability

- **HISIL Core – Functional Safety Integrated**

- Dual 200MHz ARM Cortex R5F in Lockstep
- Safe DMA transfers with CRC checks

- **AMEC – Advanced Motor Event Control**

- HW programmable Flexible Logic Unit
 - 4560 Programmable Logic Elements
 - 20x 24-bit Signal Processing Units
- Parallel access for acquisition & control



ADAPTIVE CONTROL APP (ACA)

Motor types

- PMSM (Permanent Magnet Synchronous Motor)
- WRSM (Wound Rotor Synchronous Motor)
- Axial/Radial, 3-Phases/6-Phases

Modulation

- SVPWM (Space Vector Pulse Width Modulation)
- DPWM (Discontinuous Pulse Width Modulation)
- Variable switching frequency & Dead-time compensation

Motor position sensors supported

- SIN/COS, resolver, AMR-GMR, Hall effect, etc

Motor control algorithms

- Flux Weakening management
- FOC (Field Oriented Control)
- D/Q inductances LUT
- Torque derating LUT based on Speed/DC-Link and T°
- Slew rate limitation
- Torque/Current/Speed control
- Rotor control
- Clockwise/Anti-clockwise

Motor Control APIs

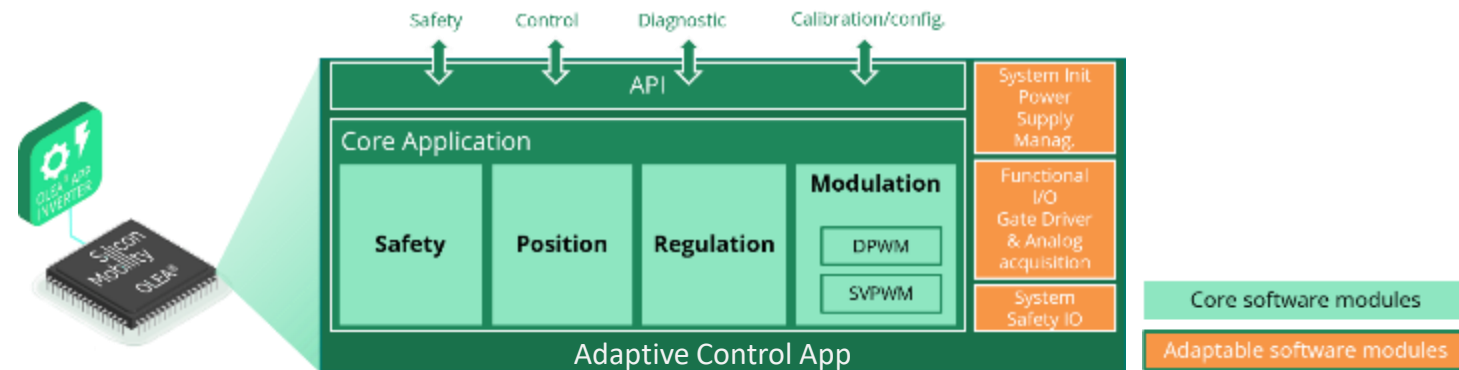
- to pilot the e-motor with Torque or Speed command
- to manage the control state (Power-up, Init, Standby, Active, Power-down, Power-off)
- to get the motion state (Drive Motion/Braking or Reverse Motion/Braking)

Safety APIs

- to manage the faults/warning such as over/under current/voltage on phases, the over-voltage on DC-Link, the over-temperature on Power Transistor or e-motor
- to get the Safe state

Diagnostics APIs

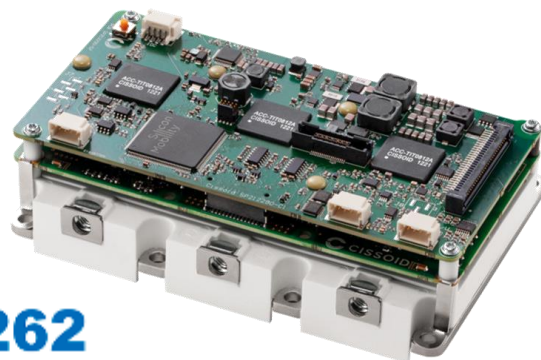
Calibration/Configuration APIs



CERTIFICATION & AVAILABILITY

INTEL/Silicon Mobility Certification

- **MCU: T222 Adaptive Control Unit (ACU)**
 - AEC-Q100 Grade 1 (-40°C to +125°C)
 - ISO26262 ASIL-D Certified
- **SW: Adaptive Control App (ACA)**
 - ISO26262 ASIL-D Certified
 - AUTOSAR 4.3



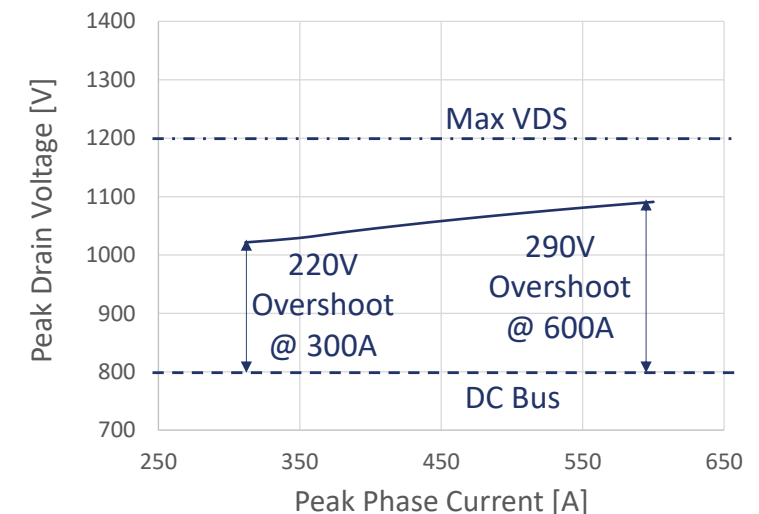
ICM Certification

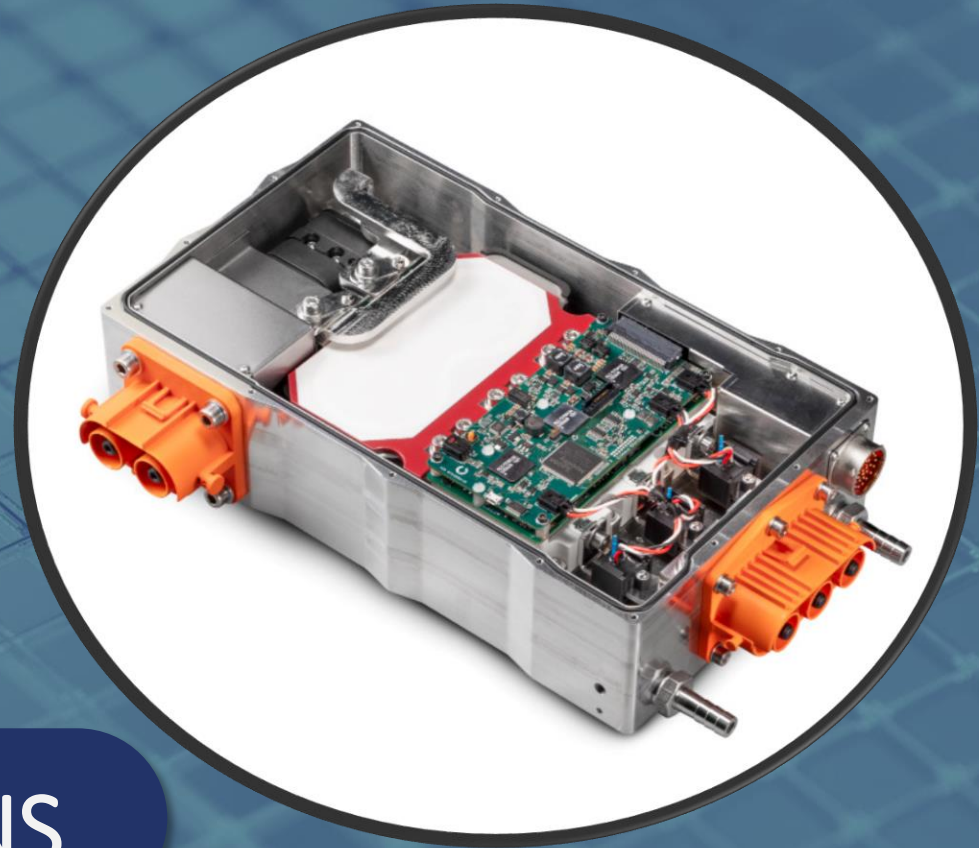
- ISO26262 ASIL-C Ready (Q1 2025)
- AQG-324 (Q2 2025)
- ISO26262 ASIL-C Certified (Q3 2025)

Ordering References	Max Output Power	Max Phase Current	Base-plate
CXT-ICM3SAI2340AAA	305kW	295A _{RMS}	Pin fin
CXT-ICM3SAI2450AAA	405kW	390A _{RMS}	Pin fin
CXT-ICM3SAI2550AAA	475kW	460A _{RMS}	Pin fin
CXT-ICM3SB12340AAA	330kW	320A _{RMS}	Flat

SiC INVERTER PLATFORM

- **Companion DC Link Capacitors for IPMs/ICMs in partnership with Advanced Conversion**
 - Capacitor range: 135 μ F to 500 μ F
 - Voltage range: 500V to 900V
 - Total loop inductance (IPM + Cap) : <18nH
 - High temperature dielectric : > 125°C
- **Power module, gate driver & DC Link Capacitor**
 - Fully characterized switching loop
 - di/dt and & dV/dt optimized to support 800V DC bus
 - Best trade-off between switching energies & drain-to-source voltage overshoot
- **3D-printed Reference Coolers**
 - With & without pressure sensors





SiC INVERTER REFERENCE DESIGNS

SiC INVERTER REFERENCE DESIGNS

- **Accelerating** SiC inverters design
- Modular design around CISSOID ICMs
- Supporting high voltage/power designs
- **Open Bill-of-Material (BOM) & step files**
- Embedding Intel Adaptive Control App ISO-26262 ASIL-D Software
- **Setup & calibration in less than a week** on a motor bench

SiC Inverter Reference Designs	Bench-top	On-board
For lab & bench testing	✓	
For in-vehicle testing		✓
Easy access to <ul style="list-style-type: none"> • All sub-components • Measurement points • Connectors 	✓	
Compact design		✓
Extensive EMC shielding		✓
Hermetically sealed		✓
Vibration resistant		✓

BENCH-TOP SiC INVERTER REFERENCE DESIGN

- Modular design up to 850V/330kW (peak, 60s)
- 3-Phase 1200V SiC Inverter Control Module
- **INTEL Adaptive Control Unit (HW) & App (SW)**
- DC & Phase current sensors
- High temperature DC Link capacitor
- **TDK CarXield® 900V/400A EMC filter**
- DC bus passive discharge
- **Liquid cooling** for power module & EMC filter

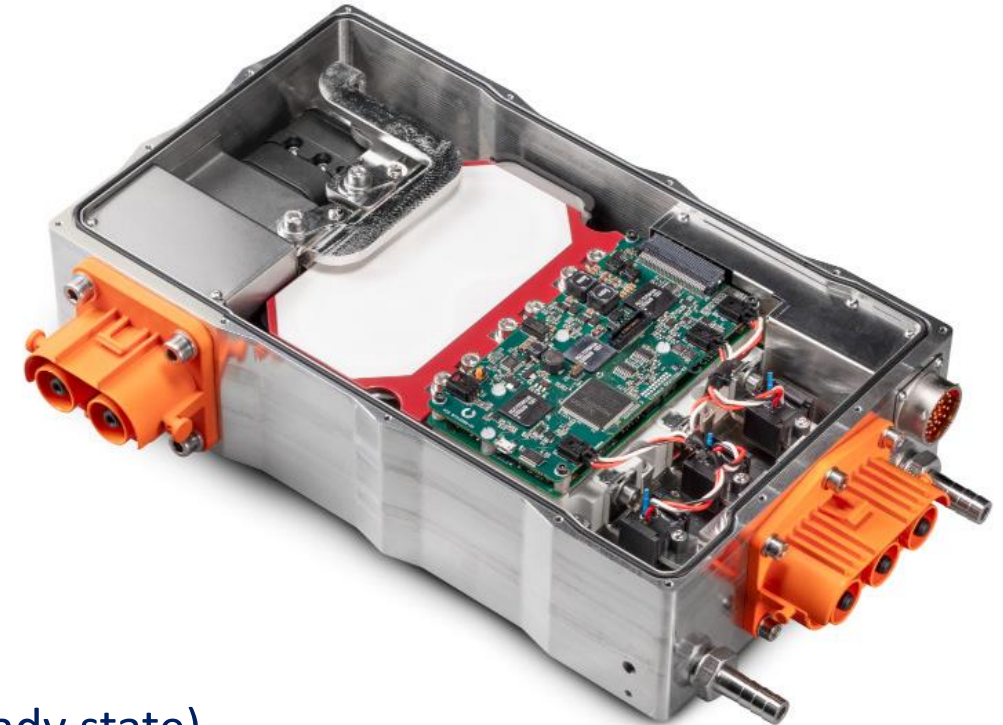
Reference	Description
EVK-PLA1050B-74	650 V _{DC} / 275 A _{RMS} / 150 kW
EVK-PLA1050B-76	650 V _{DC} / 400 A _{RMS} / 250 kW
EVK-PLA1050B-94	800 V _{DC} / 275 A _{RMS} / 200 kW
EVK-PLA1050B-96	800 V _{DC} / 400 A _{RMS} / 300 kW (includes DC link capacitor top cooling)



ON-BOARD SiC INVERTER REFERENCE DESIGN

Key characteristics

- Output power (peak, 60s): **up to 350kW**
- DC bus voltage : 100V – 850V
- Max Phase Current (steady State) : $250A_{RMS}$
(limit = Amphenol HVSL1 connector)
- Max Phase Current (peak, 60s) : **$600A_{PEAK}$**
- Output Frequency : 100 – 2000Hz
- PWM frequency : **up to 50kHz**
(power derating from 20-50kHz)
- Dimensions: 381 x 220 x 90 mm (6.73Litre)
- High power density : **52kW/litre** (peak, 60s) – 36 kW/L (steady state)



ELECTRICAL & THERMAL MODELLING

INVERTER MODEL & SIMULATION TEST BENCH FOR EMC DESIGN

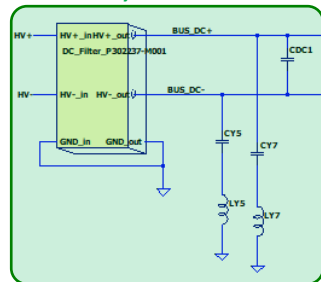


CISSOID

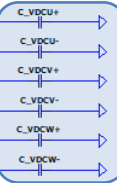
POWER SEMICONDUCTORS

- Transistor-level modelling of SiC MOSFETs
- Behavioral modelling of the gate driver
- Modelling of parasitics
- Modelling of dV/dt , dI/dt and voltage overshoots
- Modelling of SiC MOSFETs On resistance variation with temperature
- Transient thermal modelling with thermal RC network between T_{Fluid} and T_j

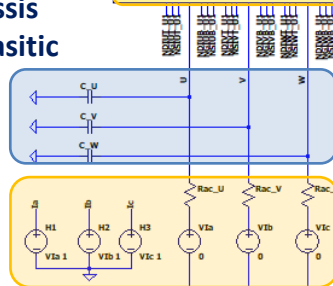
EMI Filter, DC link & Y-Cap



IPM to chassis parasitic cap

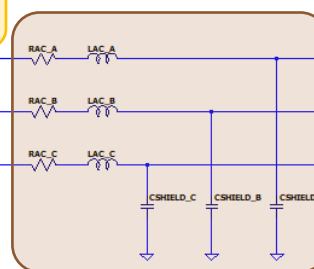


IPM to chassis parasitic cap

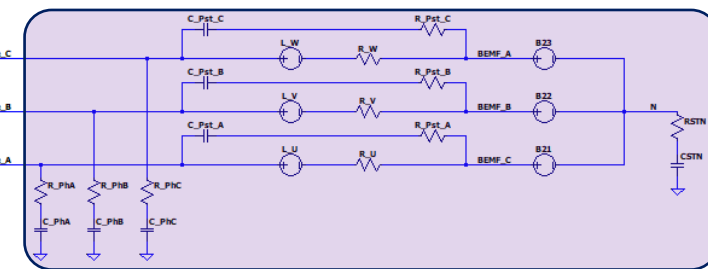


Phase Current Sensors

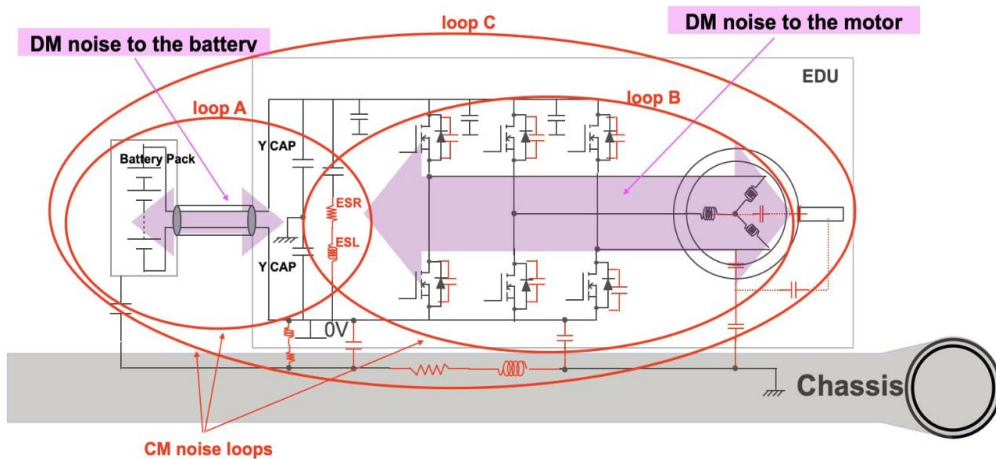
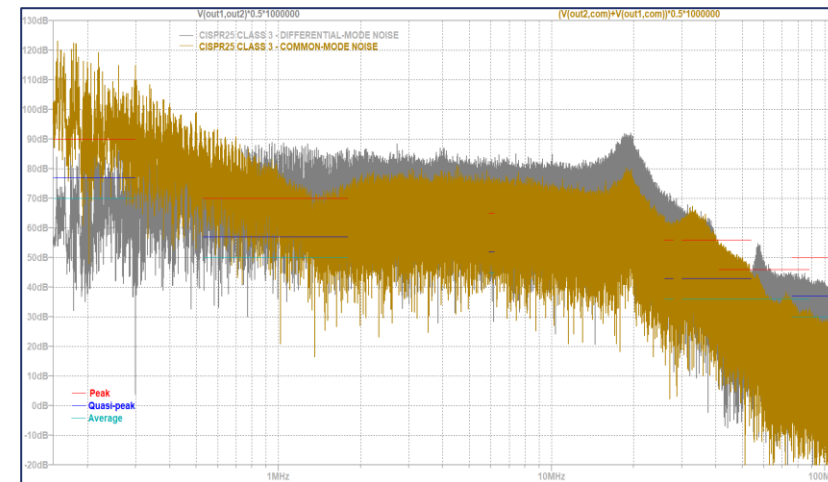
AC cables



3-Phase PMSM



Differential / Common-mode noise & CISPR25 limits

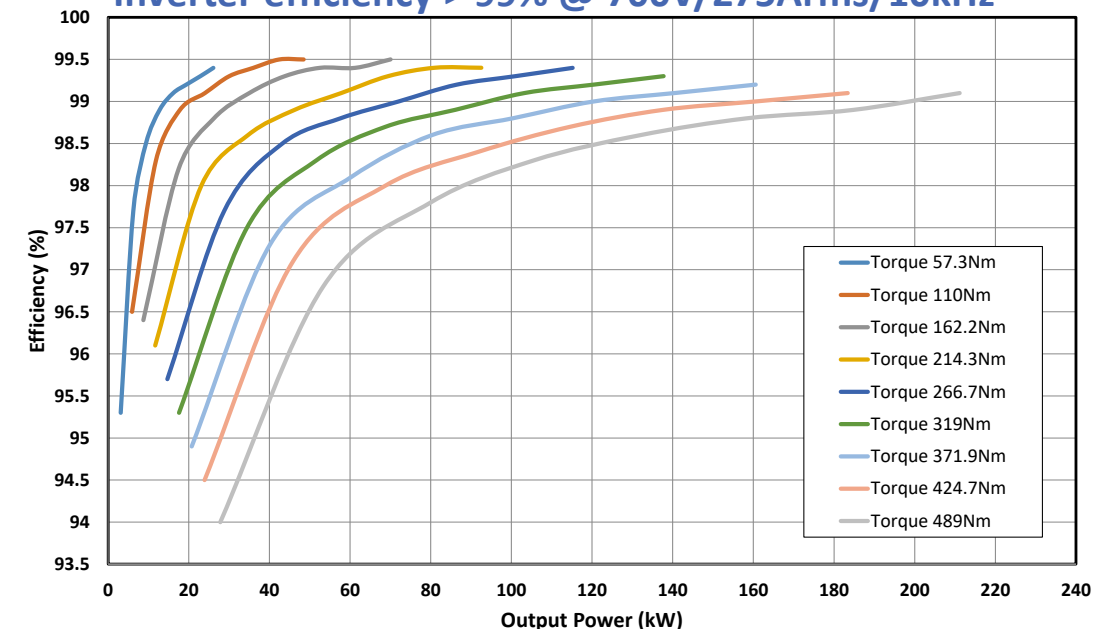


FAST E-DRIVE EVALUATION @ MOTOR BENCH

- **Step 1: Adaptive Control App software project configuration**
 - According to the e-Motor parameters
- **Step 2: Inverter/motor hardware setup**
 - Motor signal (e.g. resolver, temperature sensor) & ECU/Bench (e.g. CAN, safety) interfaces
 - Power & Cooling interfaces
 - Check that the inverter is functional @ Active state, nominal DC Link value
- **Step 3: System calibration**
 - Open loop mode
 - Current closed-loop mode (position offset calibration)
 - Partial open-loop mode (position offset validation)
 - Current close-loop mode
 - Torque control mode
 - Speed closed-loop mode (speed regulator calibration)
- **Step 4: Inverter & motor drive characterization**



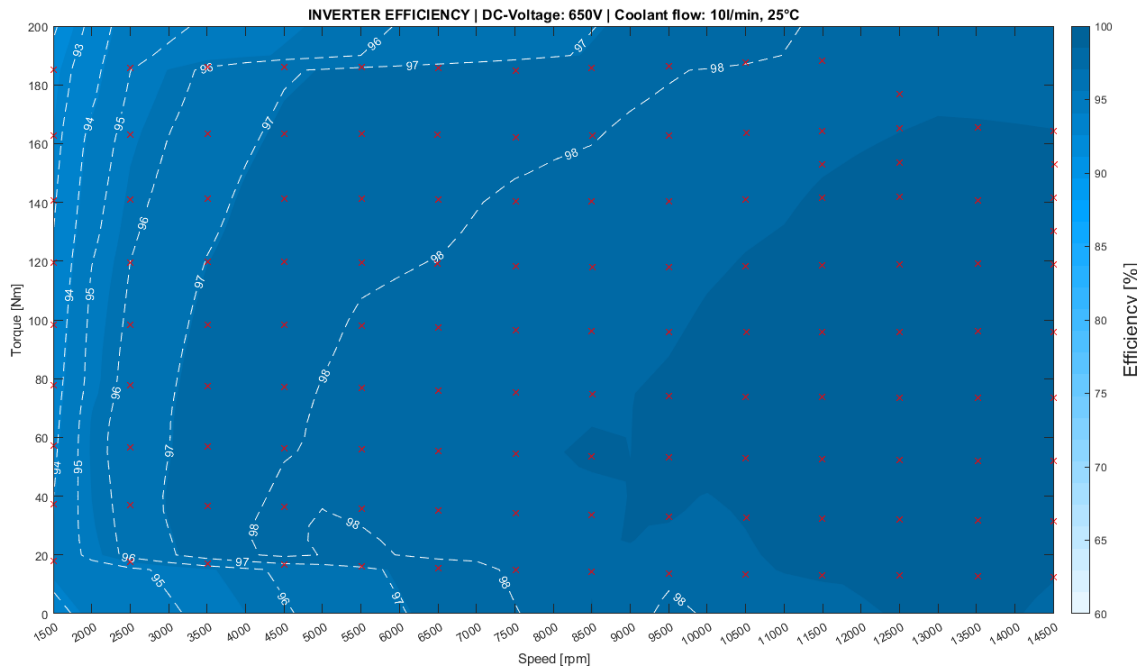
Inverter efficiency > 99% @ 700V/275Arms/10kHz



SiC VERSUS IGBT EFFICIENCY

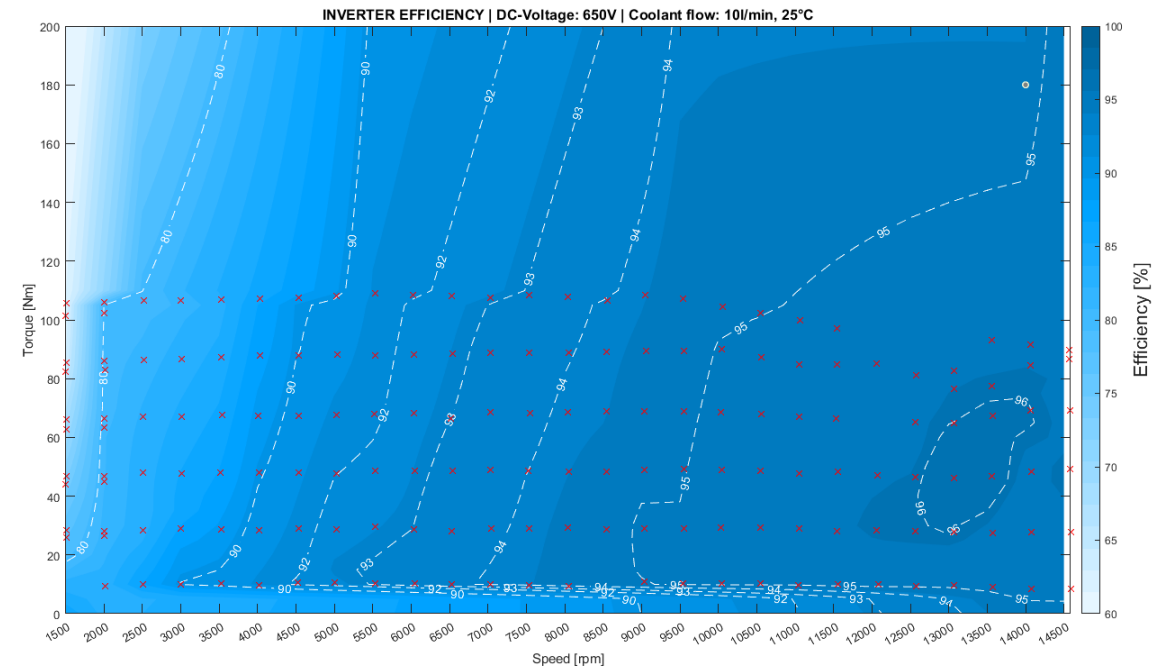
CISSOID SiC Inverter Ref Design @650V

- Max speed: 14500rpm
- Max torque: 190Nm
- Peak output power: 260kW (13500rpm)
- **Peak efficiency: 98.9%**



IGBT inverter @650V

- Max speed: 14500rpm
- Max torque: 120Nm
- Peak output power: 120kW (11500rpm)
- **Peak efficiency: 96.6%**



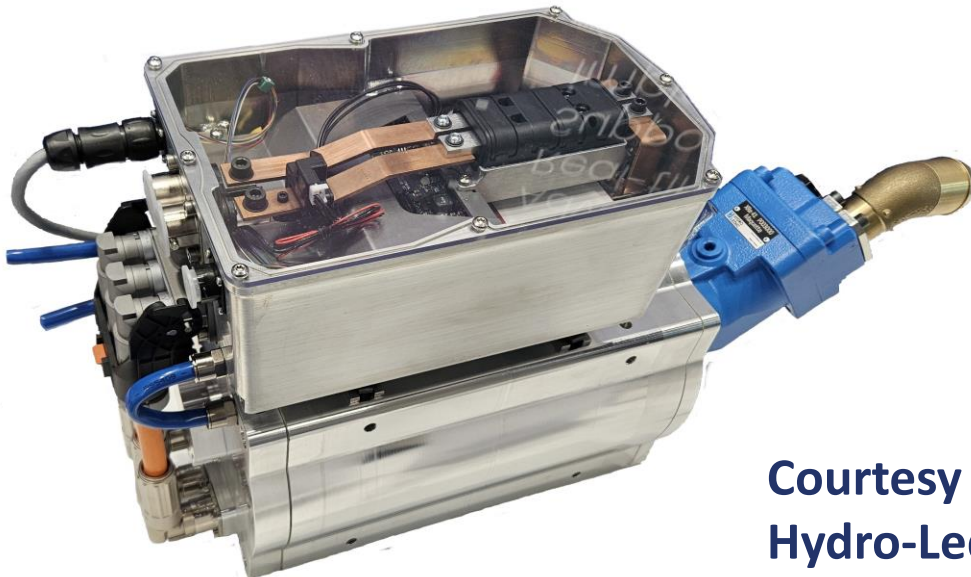
SiC Inverter maintains high efficiency even at low torque & speed !

USE CASE - ELECTRIC POWER TAKE OFF (EPTO)

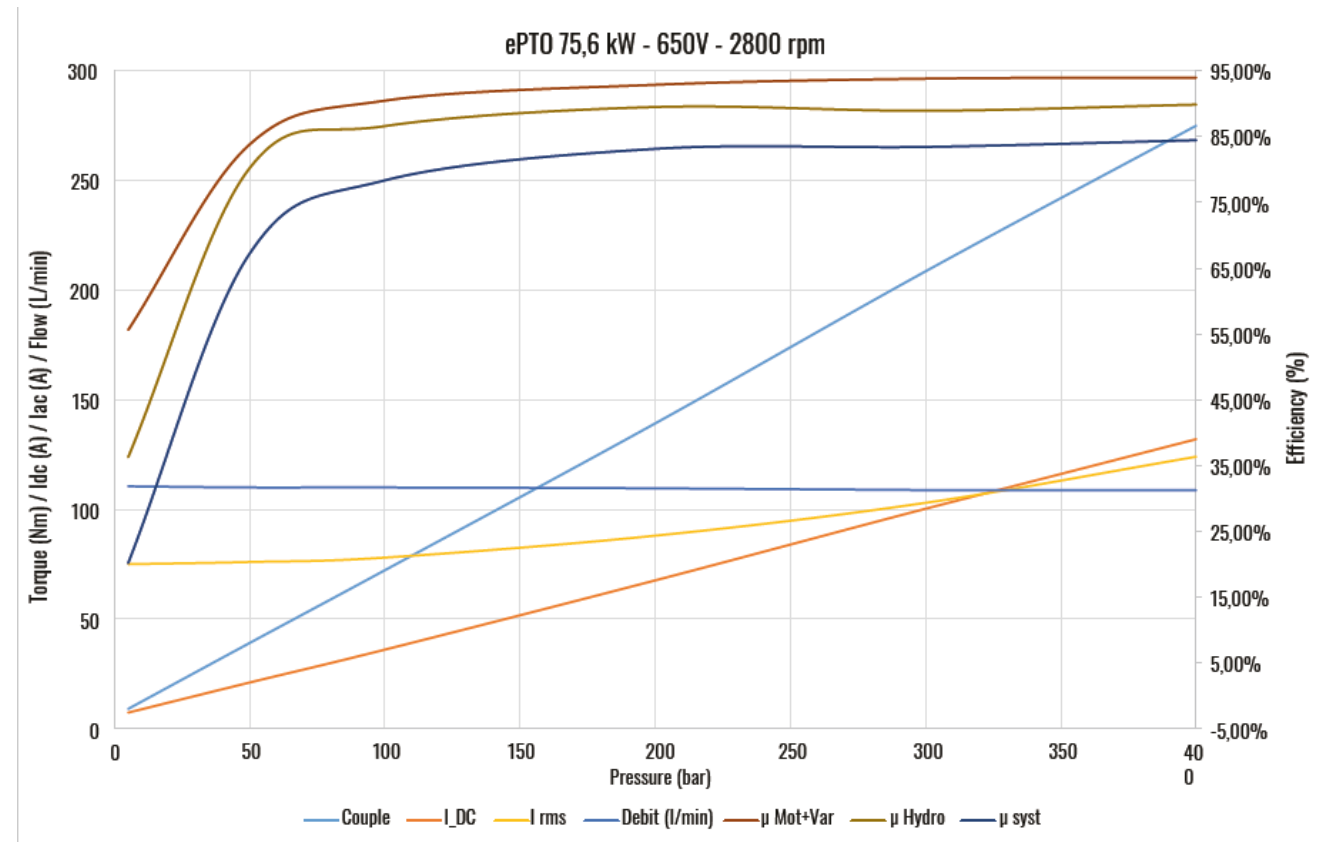
Electrification of hydraulic pump

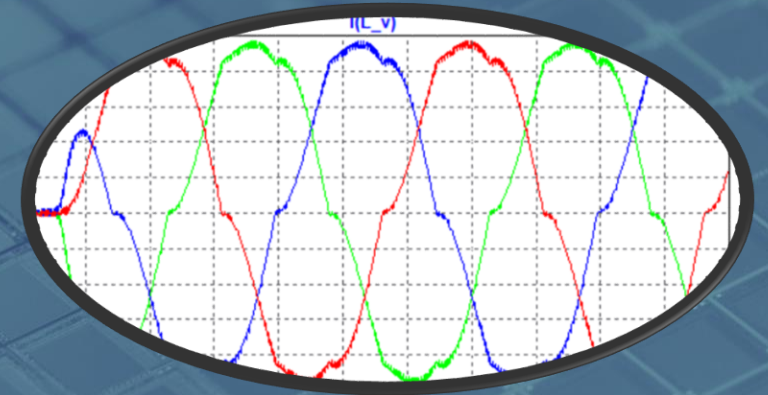
76kW / 650V / 2800rpm

- e-motor + inverter = 94% efficiency
- hydraulic pump = 89% efficiency
- system efficiency = 84%



Courtesy of
Hydro-Leduc

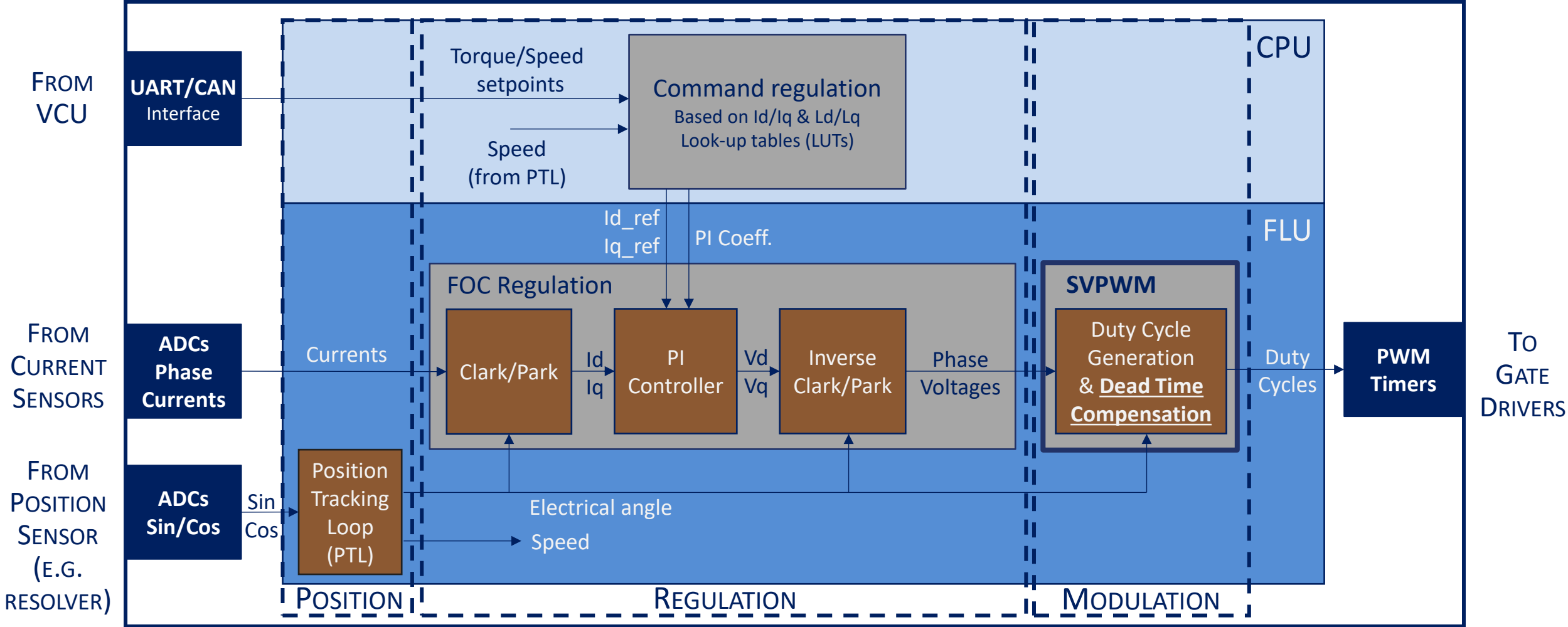




DEAD TIME COMPENSATION

DEAD TIME COMPENSATION (DTC)

PART OF INTEL ADAPTIVE CONTROL APP SVPWM MODULE



DEAD TIME COMPENSATION (DTC)

- Duty Cycle correction to **compensate the effects of the dead time**
 - Fundamental output voltage loss
 - Low-Frequency Harmonics (5th, 7th, 11th)
 - Output current and torque ripples
- Compensation $\propto V_{DC}, F_{\text{switching}}, \text{Dead time, MOSFET } t_{\text{on}} \text{ \& } t_{\text{off}} \text{ times}$
- **Case study¹: SiC Inverter + PMSM**

Inverter Parameters	Value
Inverter Control Module	CXT-ICM3SA12550AAA
Rated Inverter Power	Up to 350 kW
Rated Inverter Voltage	Up to 850 V
Rated Voltage of IPM	1200 V
Rated Current of IPM	550 A
SiC MOSFET Turn-on time T_{on}	(97+102)= 199 ns
SiC MOSFET Turn-off time T_{on}	(276+52)= 328 ns

PMSM Motor Parameters	Value
Rated Power	260 kW
Rated Torque	180 Nm
Rated Speed	14000 RPM
Number of pole pairs	4
Switching Frequency F_s	12 kHz, 16kHz
User-defined Dead time T_d	2 μ s
DC Bus Voltage V_{dc}	650 V

¹ [T. Bonnin, M. Nasir, P. Delatte, M. El Mokadem, "Implementation and Validation of a Simplified Dead Time Compensation Scheme for a High-Power Space Vector Controlled SiC Inverter PMSM Drive", 2024 IEEE Workshop on Control and Modelling for Power Electronics \(COMPEL\)](#)

SIMULATIONS IN LTSPICE

WITH AND WITHOUT DEAD TIME COMPENSATION

Case Study

Speed = 1000 Rpm, Torque= 50 Nm

SIMULATION PARAMETERS

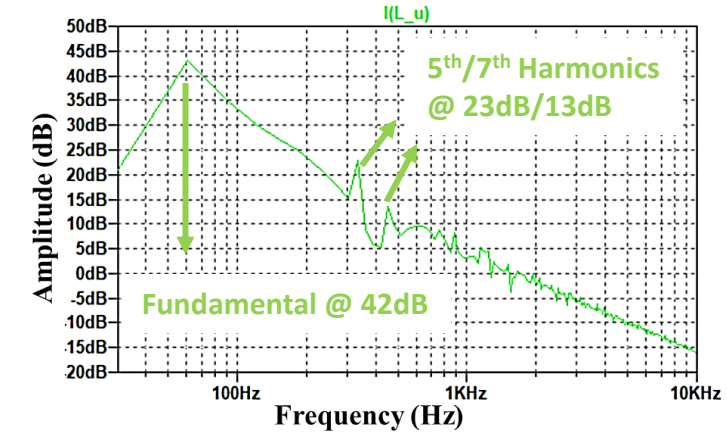
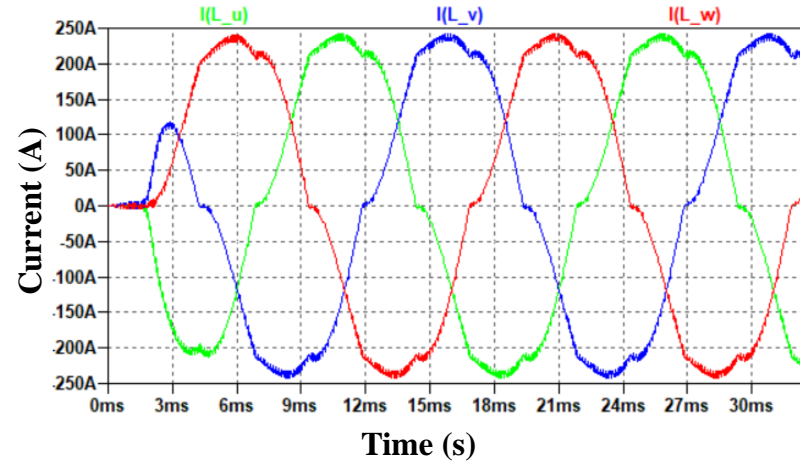
■ SPECIFIC INPUT DATA

- High Voltage Battery Voltage : 650 V
- DC-link Capacitor : 320 uF / 750 V
- ICM CXT-PLA3SA12550AA : 1200 V / 550A
- SVPWM modulation
- Dead time = 2 μ s
- Fswitching = 16 kHz

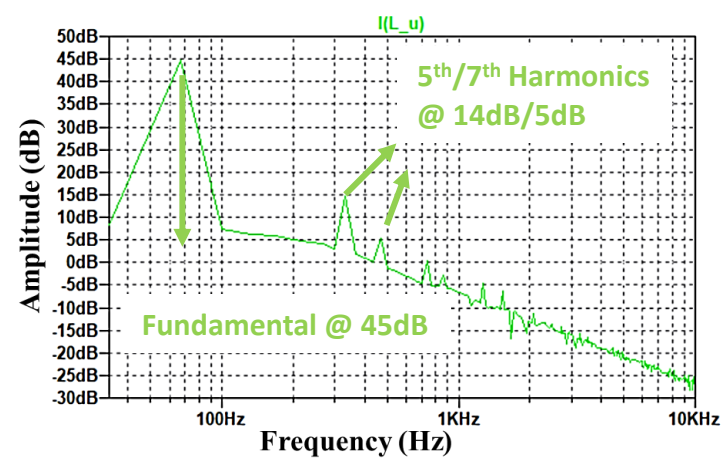
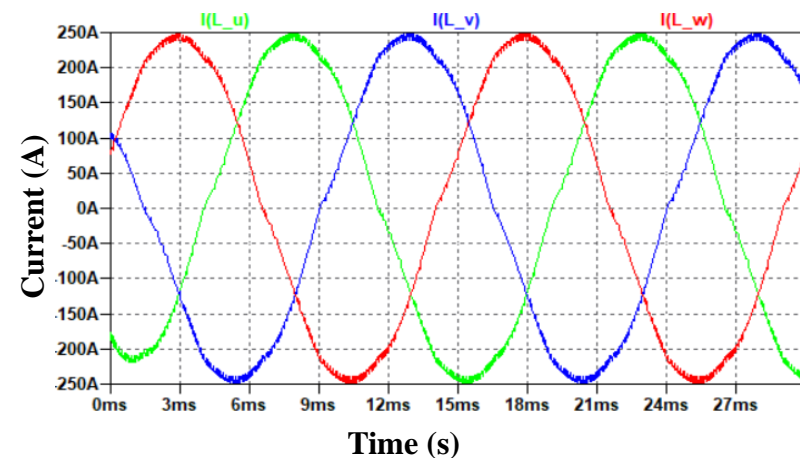
• PMSM CHARACTERISTICS

- Number of pole pairs : 4
- Flux linkage : 0.048 Wb
- D-axis inductance : 55 μ H
- Q-axis inductance : 150 μ H
- Stator self-inductance : 160 μ H
- Stator self-resistance : 0.008 Ω

WITHOUT DEAD TIME COMPENSATION



WITH DEAD TIME COMPENSATION

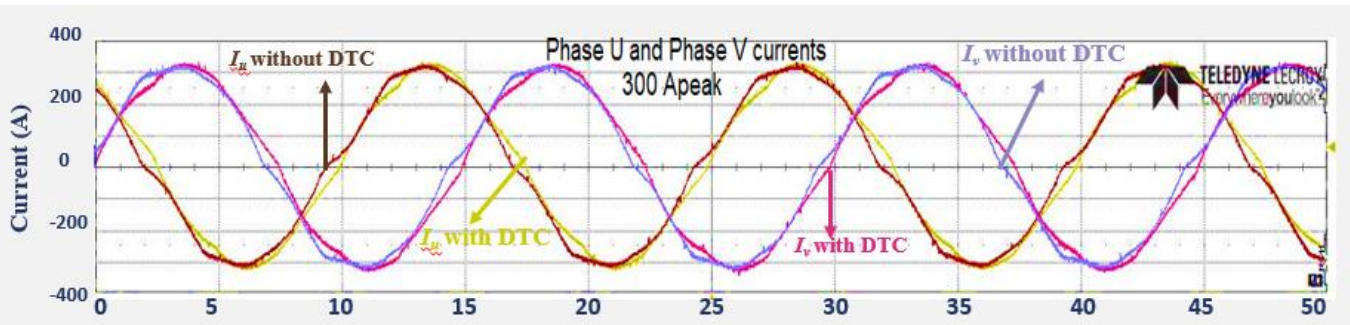


DTC - MOTOR BENCH VS SIMULATIONS

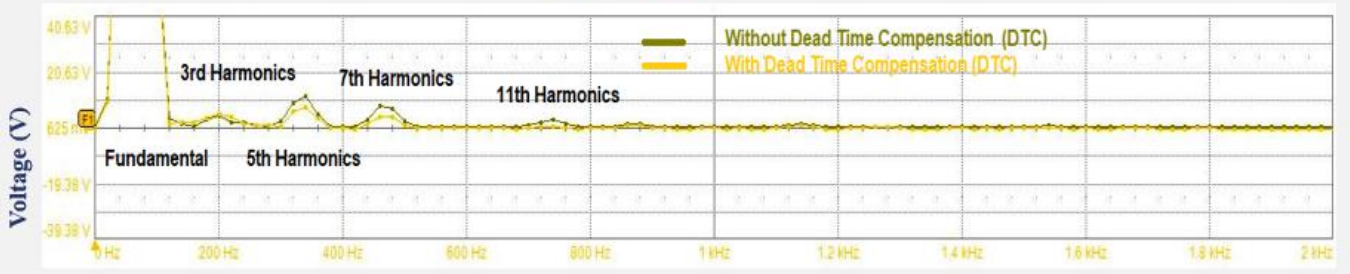
CASE STUDY: SPEED = 1000 RPM, Torque= 50 Nm



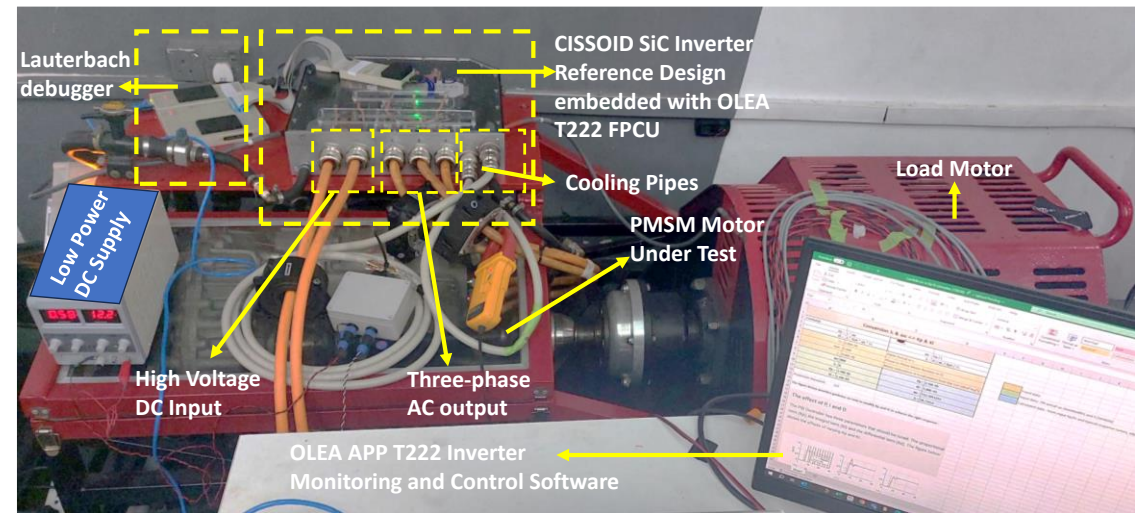
MOTOR BENCH DATA



(a) Time (ms)



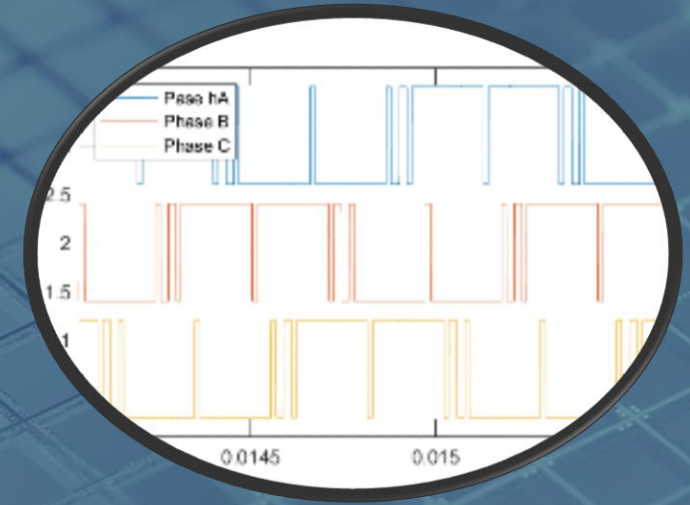
(b) Frequency (Hz)



COMPARATIVE ANALYSIS

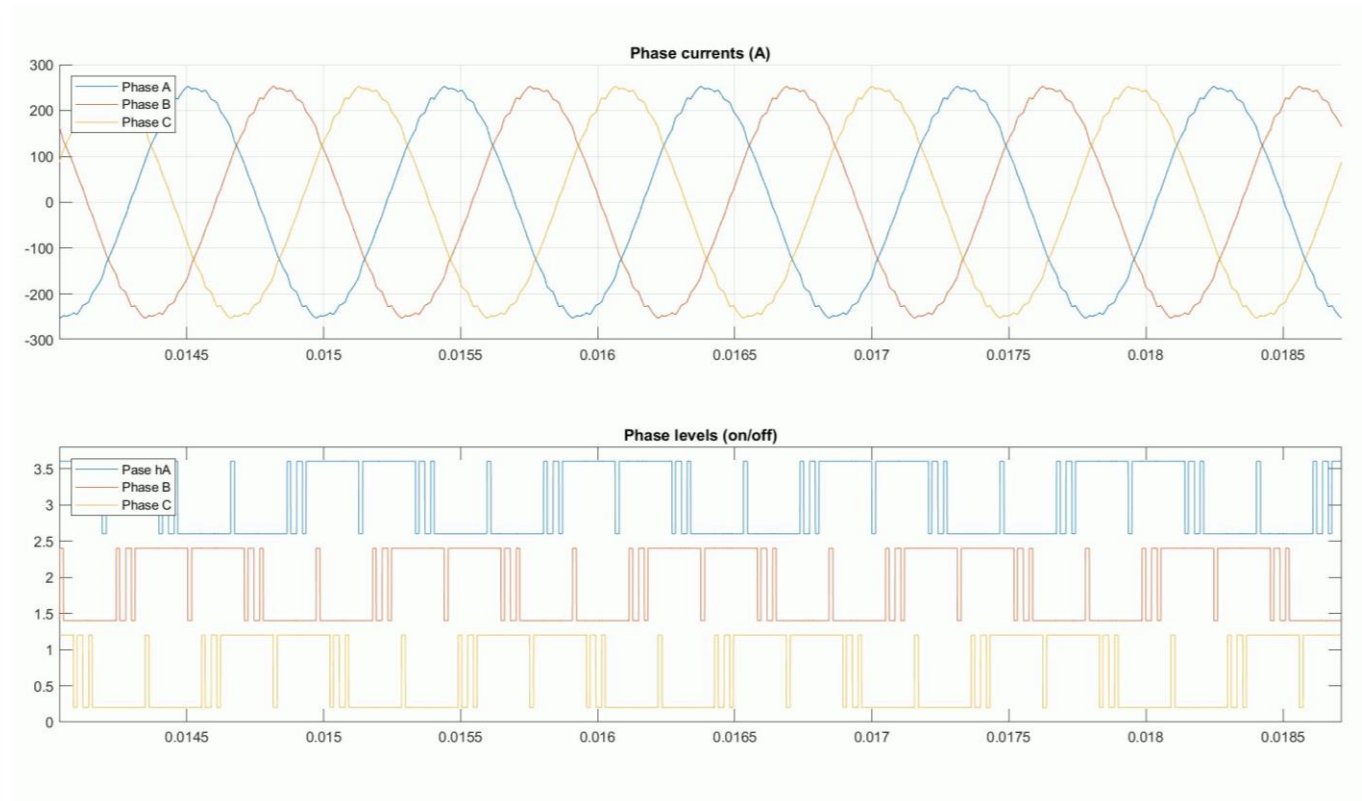
	I_u FFT (simulations)				I_u FFT (motor bench)			
	Fund. Normalized (%)	5 th Normalized (%)	7 th Normalized (%)	THD (%)	Fund. Normalized (%)	5 th Normalized (%)	7 th Normalized (%)	THD (%)
W/O DTC	100	6.2	3.2	7.3	100	8.9	5.4	7.8
With DTC	101.4	2.6	1.2	3.1	101	5.4	2.8	4.7
Improv.(%)	1.4	59	63	4.2	1	39	48	3.1

Improvement in phase current THD thanks to DTC demonstrated both in simulations and on the bench !



OPTIMIZED PULSE PATTERNS

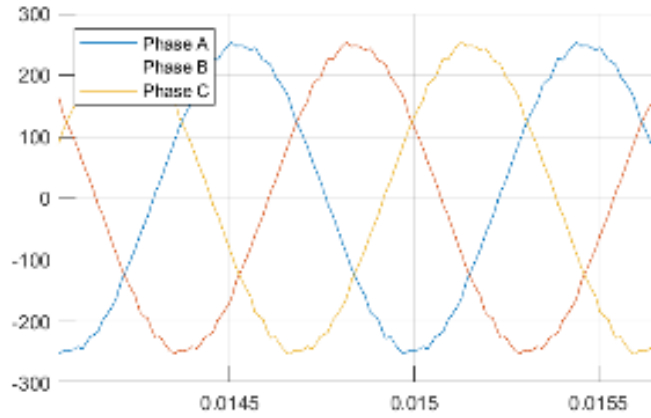
OPTIMIZED PULSE PATTERNS



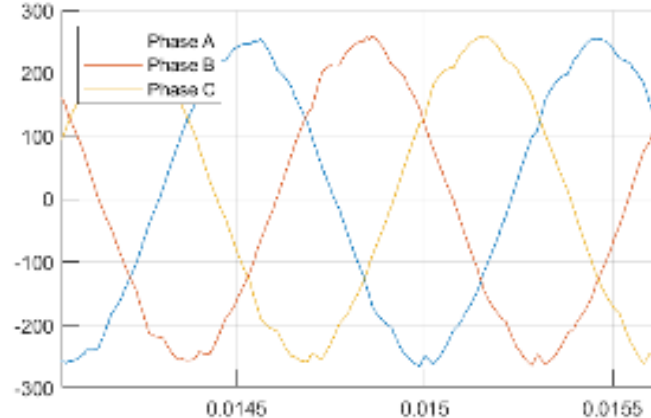
- A control method replacing conventional modulations as SVPWM, DPWM, SIX STEPS, etc.
- Based on the electrical angle:
Not time-based as SVPWM modulation
- OPP applies a switching pulse pattern repetitively at each electrical period.
- No PWM carrier : **full freedom to locate switching pulses** at any angular position.
- Optimized for a motor speed-torque range.
- OPPs are generated offline in a digital process using tuned models of the inverter and motor

CISSOID's SiC Inverter solutions offer a ready-to-use hardware platform for Intel Automotive's Adaptive Control App (ACA) and its high-performance OPP modulation

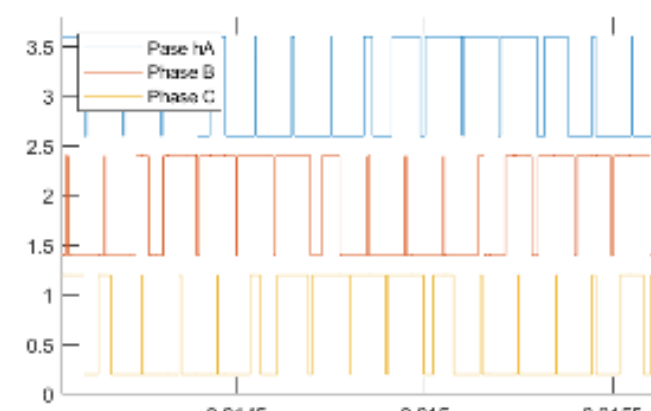
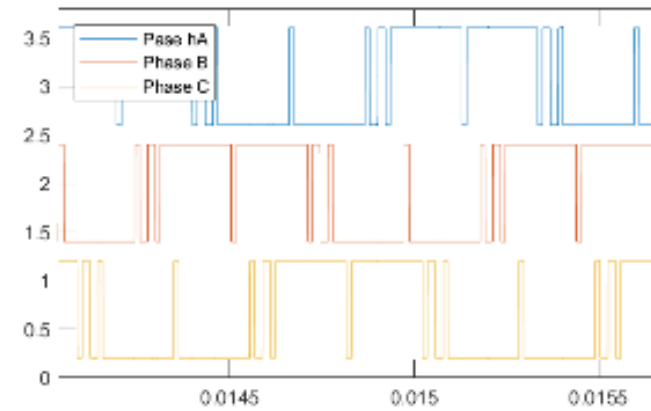
OPP vs SVPWM GATE CONTROL



OPP



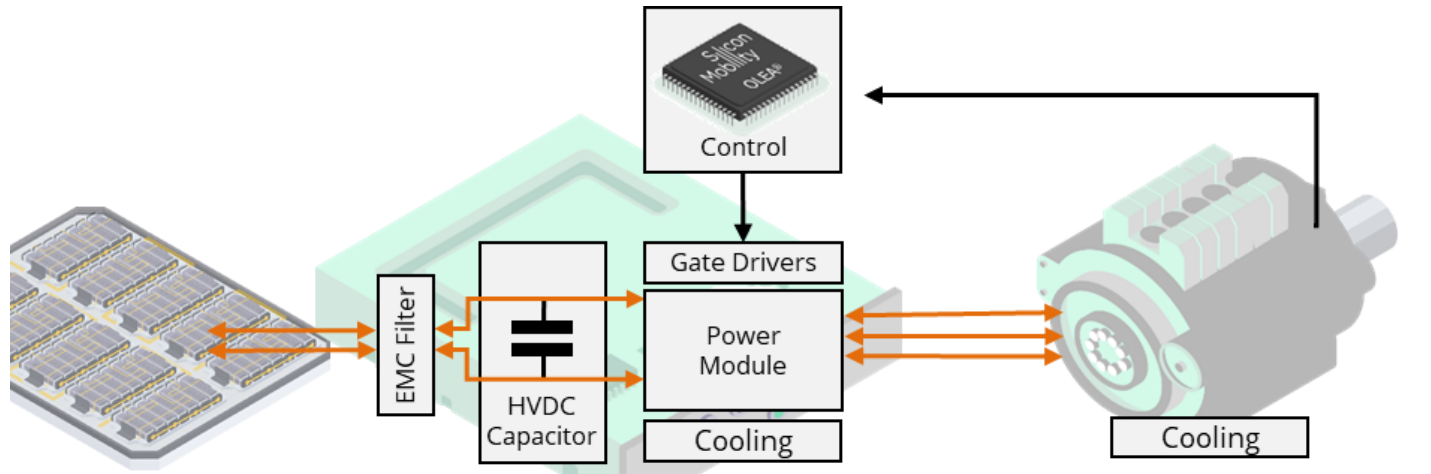
SVPWM



Number of switching pulses and related angle positions are determined to optimize the modulation **upon different criteria:**

- Inverter losses
- E-motor losses
- Total Harmonic Distortion (THD)
- Noise, Vibration and Harshness (NVH)
- Current ripple

OPP BENEFITS



Battery Benefits	Inverter Benefits		Motor Benefits	
Smaller capacity	Lower energy losses	Downsizing of passive components	Lower energy losses	Smaller, higher revving motors
Less volume / weight	Lower cooling demand	Higher power density	Lower NVH	lower mass
			Lower cooling demand	

← Vehicle Benefits: less weight & cost →

Motor & inverter benefits

- Up to 5% efficiency gain (inverter & motor) at critical load points
- Control of electrical machines revving supporting 100.000 rpm and above
- 20% higher torque out of the same motor or 20% lower battery voltage by extended overmodulation
- Tuneable, Improved NVH behaviour

Vehicle benefits

- Cost & weight savings by motor downsizing
- Cost & weight savings by DC-Link capacitor downsizing by 2 and reducing by 40% the peak cooling demands (Inverter)
- Cost & weight savings from lower battery voltage or higher power/peak torque out of the same motor
- Cost & weight savings from lower sound-insulation requirements



SUMMARY

UNIQUE INVERTER SOLUTIONS

Modular & open platform

1

Footprint-compatible power modules make it easy to vary up and down in power range, according to the needs across vehicle families. Controller solutions can be provided or swapped for in-house developments.

Highly Modifiable

3

Most parts of the design, from the semiconductor components to the software and the mechanical design, can be adapted to the application's needs.

Single Point of Contact

5

Single point of contact for technical support on hardware and software

Easy, proven solution

2

A proven design, tested across a wide range of use cases, up and running within days

Components to Software

4

Single supplier from individual components over control boards to motor control software and reference designs



CISSOID

POWER SEMICONDUCTORS

QUESTIONS?

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